Mark IV Delta Tau Labview Change Log

Mark IV User interface Deltat Tau TCP alt Interface

Added second distance to target/Act Move complete to Micro Move Screen

Moved and labeled Distanc to target and Act move complete

Updated error handling for com errors to set System Error but not stop run.

Updated Soft limits to allow values not centered on zero I.E. -3 to -8

**Changed Actuator moves to go through kinematics to prevent passive rail crash and to apply soft limits (This could have been a big problem!!!)**

Changed update values on tab change to happen immediately. (was using OldVal to determing what to update needed to be NewVal

Still need to clean up “Move Actuator” Event

Before new build update Gui System images